# COMPUTER CONTROLLED PAN-TILT UNIT Models PTU-D46



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## COMPUTER CONTROLLED PAN-TILT UNIT Models PTU-D46-17 & PTU-D46-70

### **Technical Specifications**

#### **General Features**

- Simple to use from any RS-232 terminal or computer
- Fast and accurate camera positioning at low cost
- Precise control of position, speed & acceleration
- Small form factor
- Allows on-the-fly position and speed changes
- Self calibration upon reset
- Power consumption can be controlled from host
- ASCII command mode for simplicity, binary commands available for efficient program control
- DC power input from an unregulated source
- · Radiation hardened
- CE Mark certified for Europe

#### **Pan-Tilt Performance**

MODEL	PTU-D46-17	PTU-D46-70
Rated payload	6 lbs (2.72kg)	9 lbs (4.08kg)
Max. unloaded speed (@30VDC)	300°/second	60°/second
Resolution	3.086 arc minutes (0.051428°)	0.771 arc minutes (0.012857°)

**Acceleration/Deceleration:** Trapezoidal. On-the-fly speed and position changes.

**Tilt Range (approx):** minimum 31° up and 47° down (78° range) with extended range mode of 80° down (111° range)

Pan Range (approx):  $\pm 159^{\circ}$  (318° range) with extended range mode of  $\pm 180^{\circ}$  (360° range)

#### **Power Requirements**

Input Voltage: 8-30VDC unregulated

**Power Consumption:** 

13W continuous peak (full-power mode) 6W continuous peak (low-power mode) 1W continuous peak (holding power off mode)

#### Mechanical

#### Pan-Tilt Unit:

- **− Weight:** 3 lb.
- Dimensions: 3" wide x 5.13" high x 4.25" deep
- Camera mounting: Hole for 1/4-20 screw standard.
   Camera mounting plate removes for easy customizing.
- **Pan-tilt unit mounting:** Bottom or front 1/4-20 mounting

#### Controller:

- Weight: 8 oz.

Specifications subject to change without notice.

#### **Built-In Connectivity Capabilities**

**Basic Mode:** Host RS-232 port controls single pan-tilt unit **Extended Mode:** Control of multiple pan-tilt units from one or more host computers. Multidrop RS-485 network using RJ-12.

#### **Host Control**

**Host:** RS-232 (default is 9600 baud, 1 start bit, 8 data bits, 1 stop bit, no parity, no handshaking). DB-9 female connector.

**Host modes:** Interactive Mode (ASCII command set) and Encoded Mode (binary format for higher bandwidth computer control)

#### **Commands include:**

<axis> is T for the tilt axis or P for the pan axis.

#### **Axis Control Commands:**

**General form:** <axis><command><value><delim> ⇒ [<status>]

Go to position:  $\langle axis \rangle P \langle position \rangle \langle delim \rangle \Rightarrow [\langle status \rangle]$ 

Go to offset position:  $\langle axis \rangle O \langle relative position \rangle \langle delim \rangle \Rightarrow [\langle status \rangle]$ 

Set target speed: <axis>S<positions/sec><delim> ⇒ [<status>]
Set acceleration: <axis>A<positions/sec²><delim> ⇒ [<status>]

Set speed bounds:  $\langle axis \rangle | U | L \rangle \langle bxis \rangle | c \rangle \langle c \rangle | c \rangle$ 

Move power mode:

 $<axis>M[<hi power> | <reg power> | <lo power>]<delim> <math>\Rightarrow$ [<status>]

Hold (stationary) power mode:

 $<axis>H[<reg power> | <lo power> | <power off> ]<delim> <math>\Rightarrow$ [<status>]

#### Axis Queries:

General form: <axis><command><delim> ⇒ <query answer>
(Axis Control Commands become queries when the <value> argument

**Resolution:** <axis>**R**<delim $> \Rightarrow <$ arc seconds per position>**Position bounds:** <axis>[**N** | **X**]<delim $> \Rightarrow <$ boundary position>

Unit Commands:

Command menu: ?<delim> ⇒ <menu>
Await completion: A<delim> ⇒ <status>
Reset unit: R<delim> ⇒ [<status>]
Immediate mode: I<delim> ⇒ [<status>]
(immediate position command execution)

**Slaved mode: S**<delim>⇒ [<status>]

(position commands execute upon Await Completion command)

**Defaults:** D[<save> | <restore> | <factory settings>]<delim> ⇒ [<status>] (Saves and restores unit defaults at power up)

#### **Available Options**

- International AC/DC Power Supply (model PT-PS-INT30V)
- Weatherized option provides outdoor use (add "W" to PTU model)
- Nodal (gimbal) pan-tilt adaptor
  - Payload can mount at the intersection of the pan and tilt axes
  - Uses include rotating camera at focal point & mirror positioning
- C Programmer's Interface (model PTU-CPI)
- PTU network cabling kits available
- Trackball and analog joystick interfaces available



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